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Present group members:

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**Worksheet 2-2: Q1**

For the following symmetric matrices, cross out the classifications it **CANNOT** be due to the diagonal entries (don't calculate the eigenvalues).

•  $A_1 = \begin{bmatrix} 0 & 1 \\ 1 & 5 \end{bmatrix}$

*pos def*   *pos semidef*   *indefinite*  
*neg def*   *neg semidef*

*Can't be negative definite or negative semidefinite because diagonal entry of 5 is positive. Also can't be positive definite because diagonal entry of 0 is not positive. Remaining options are positive semidefinite or indefinite.*

•  $A_2 = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$

*pos def*   *pos semidef*   *indefinite*  
*neg def*   *neg semidef*

*Can't be negative definite or negative semidefinite because diagonal entries are positive. Remaining options are positive definite, positive semidefinite, or indefinite.*

•  $A_3 = \begin{bmatrix} -1 & 2 \\ 2 & 1 \end{bmatrix}$

*pos def*   *pos semidef*   *indefinite*  
*neg def*   *neg semidef*

*Only option is indefinite because one diagonal entry is positive and one is negative.*

•  $A_4 = \begin{bmatrix} -3 & 1 \\ 6 & -2 \end{bmatrix}$

*pos def*   *pos semidef*   *indefinite*  
*neg def*   *neg semidef*

*Can't be positive definite or positive semidefinite because diagonal entries are negative. Remaining options are negative definite, negative semidefinite, or indefinite.*

For the following matrices with their given eigenvalues, what is the correct classification and why?

$$\bullet A_1 = \begin{bmatrix} 0 & 1 \\ 1 & 5 \end{bmatrix}; \text{ eigvals} = \{-0.193, 5.193\}$$

*pos def    pos semidef    indefinite*  
*neg def    neg semidef*

*Indefinite because one positive and one negative eigenvalue*

$$\bullet A_2 = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}; \text{ eigvals} = \{0.382, 2.618\}$$

*pos def    pos semidef    indefinite*  
*neg def    neg semidef*

*Positive definite because all eigenvalues are positive*

$$\bullet A_3 = \begin{bmatrix} -1 & 2 \\ 2 & 1 \end{bmatrix}; \text{ eigvals} = \{-2.236, 2.236\}$$

*pos def    pos semidef    indefinite*  
*neg def    neg semidef*

*Indefinite because one positive and one negative eigenvalue*

$$\bullet A_4 = \begin{bmatrix} -3 & 1 \\ 6 & -2 \end{bmatrix}; \text{ eigvals} = \{-5, 0\}$$

*pos def    pos semidef    indefinite*  
*neg def    neg semidef*

*Negative semidefinite because eigenvalues are either negative or 0.*

**Worksheet 2-2: Q2** On the last worksheet, we found the stationary points of the function

$$f(x, y) = 6x^2y - 3x^3 + 2y^3 - 150y$$

were at  $p_1 = (0, 5)$   $p_2 = (0, -5)$   $p_3 = (4, 3)$   $p_4 = (-4, -3)$ . Use the second optimality condition to classify each stationary point as a local minimum, local maximum, or saddle point.

You may use a computational tool to compute eigenvalues for you (although in these examples you shouldn't have to!). You can visually check your answer at [desmos.com/3d/xa4komuwmb](https://www.desmos.com/3d/xa4komuwmb).

- $\nabla f(x) = \begin{bmatrix} 12xy - 9x^2 \\ 6x^2 + 6y^2 - 150 \end{bmatrix}$

- $\nabla^2 f(x) = \begin{bmatrix} 12y - 18x & 12x \\ 12x & 12y \end{bmatrix}$

- At  $p_1 = (0, 5)$ ,  $\nabla^2 f(p_1) = \begin{bmatrix} 60 & 0 \\ 0 & 60 \end{bmatrix}$ . This has eigenvalues 60 and 60 (yay for diagonal matrix!) which are both positive, so it is positive definite  $\implies$  local minimum.

- At  $p_2 = (0, -5)$ ,  $\nabla^2 f(p_2) = \begin{bmatrix} -60 & 0 \\ 0 & -60 \end{bmatrix}$ .

This has eigenvalues -60 and -60 (again easy because it's a diagonal matrix) which are both negative, so it is negative definite  $\implies$  local maximum.

- At  $p_3 = (4, 3)$ ,  $\nabla^2 f(p_3) = \begin{bmatrix} -36 & 48 \\ 48 & 36 \end{bmatrix}$ .

This has eigenvalues 60 and -60 (using a computational tool) which have opposite signs, so it is indefinite  $\implies$  saddle point.

Note, can also see that it is indefinite because it has one positive and one negative diagonal entry.

- At  $p_4 = (-4, -3)$ ,  $\nabla^2 f(p_4) = \begin{bmatrix} 36 & -48 \\ -48 & -36 \end{bmatrix}$ .

This also has eigenvalues 60 and -60 (using a computational tool) which have opposite signs, so it is indefinite  $\implies$  saddle point.

Note, can also see that it is indefinite because it has one positive and one negative diagonal entry.

### Worksheet 2-2: Q3

Find and classify the stationary points of  $f(x, y) = 2x^3 + 3y^2 + 3x^2y - 24y$

- $\nabla f(x, y) = \begin{bmatrix} 6x^2 + 6xy \\ 6y + 3x^2 - 24 \end{bmatrix}$

- Set gradient to 0 to find stationary points

- From the first equation  $6x^2 + 6xy = 6x(x + y) = 0$  means either  $x = 0$  or  $y = -x$
- From the second equation  $6y + 3x^2 - 24 = 0 \implies y = -\frac{1}{2}x^2 + 4$

- If  $x = 0$ , then from second equation  $y = 4$  so one stationary point is at  $(0, 4)$
- If  $y = -x$ , then substituting into second equation gives

$$\begin{aligned} 6(-x) + 3x^2 - 24 &= 0 \\ 3x^2 - 6x - 24 &= 0 \\ x^2 - 2x - 8 &= 0 \\ (x - 4)(x + 2) &= 0 \end{aligned}$$

So  $x = 4$  or  $x = -2$ .

- If  $x = 4$ , then  $y = -4$  so another stationary point is at  $(4, -4)$
- If  $x = -2$ , then  $y = 2$  so another stationary point is at  $(-2, 2)$

- So the stationary points are at  $(0, 4)$ ,  $(4, -4)$ , and  $(-2, 2)$
- Next, compute the Hessian

$$\nabla^2 f(x, y) = \begin{bmatrix} 12x + 6y & 6x \\ 6x & 6 \end{bmatrix}$$

- Evaluate Hessian at each stationary point and classify

- At  $(0, 4)$ ,  $\nabla^2 f(0, 4) = \begin{bmatrix} 24 & 0 \\ 0 & 6 \end{bmatrix}$  This has eigenvalues 24 and 6 (yay for diagonal matrix!) which are both positive, so it is positive definite  $\implies$  local minimum.
- At  $(4, -4)$ ,  $\nabla^2 f(4, -4) = \begin{bmatrix} 24 & 24 \\ 24 & 6 \end{bmatrix}$  This has eigenvalues 40.63 and  $-10.63$  (using a computational tool) which have opposite signs, so it is indefinite  $\implies$  saddle point.
- At  $(-2, 2)$ ,  $\nabla^2 f(-2, 2) = \begin{bmatrix} -12 & -12 \\ -12 & 6 \end{bmatrix}$  This has eigenvalues  $-18$  and  $12$  (using a computational tool or by hand) which have opposite signs, so it is indefinite  $\implies$  saddle point.

- Visual check: [desmos.com/3d/juzovyr3hd](https://www.desmos.com/3d/juzovyr3hd)